

Simscape™ Fluids™ Release Notes



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Simscape™ Fluids™ Release Notes

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R2017b

Version: 2.3

New Features

Bug Fixes

Variable-Displacement Motor (TL) and Variable-Displacement Pump (TL) Blocks: Model motors and pumps with variable displacement

Model thermal liquid pumps and motors with variable displacement. The **Thermal Liquid > Pumps and Motors** library provides two new blocks for this purpose: Variable-Displacement Motor (TL) and Variable-Displacement Pump (TL). Exposed on each block is a physical signal port for the input of the displacement signal. Connect this port to specify the volume of fluid swept in a stroke as a function of time or as a constant.

Thermal Liquid Pumps and Motors with Variable Losses and Efficiencies: Specify loss or efficiency as tabulated data or input signals

Specify loss or efficiency in a thermal liquid pump or motor as a variable input. Both fixed- and variable-displacement pumps and motors now include variable loss and efficiency variants. You can represent these components using the blocks provided in the **Thermal Liquid > Pumps and Motors** library:

- Fixed-Displacement Motor (TL)
- Fixed-Displacement Pump (TL)
- Variable-Displacement Motor (TL)
- Variable-Displacement Pump (TL)

Use the context-sensitive menu of the block to select a block variant. Right-click the block, then, from the **Simscape > Block Choices** menu, select `Input losses` or `Input efficiencies`. The block exposes two physical signal input ports, one for mechanical loss or efficiency, the other for volumetric loss or efficiency.

Tank (G-TL) Block: Model tanks with both thermal liquid and gas inlets

Model a tank with thermal liquid and gas volumes. The **Fluid Network Interfaces > Tanks & Accumulators** library provides a new block for this purpose: Tank (G-TL). The thermal liquid and gas volumes are unmixed, as though separated by an impermeable membrane. Their pressures are assumed to be at equilibrium and are therefore always equal. The hydrostatic pressure differences between the liquid-gas interface and the thermal liquid inlets are included in the model.

This block serves as an interface between the distinct Simscape domains of Thermal Liquid and Gas. Two gas ports connect to the gas volume. An optional number of thermal

liquid ports, ranging from one to three, connect to the thermal liquid volume. Change the block variant to change the number of thermal liquid ports. Right-click the block and, from the **Simscape > Block Choices** menu, select `One inlet`, `Two inlets`, or `Three inlets`.

Simple Heat Exchanger Blocks: Model heat transfer between gas networks or gas and liquid networks using the specific dissipation method

Model heat exchange between two gases, between a gas and a thermal liquid, or between a gas and an external fluid with properties controlled by physical signals. The **Fluid Network Interfaces > Heat Exchangers** library provides three new blocks for this purpose: `Simple Heat Exchanger (G)`, `Simple Heat Exchanger (G-G)`, and `Simple Heat Exchanger (G-TL)`.

The heat transfer rate is calculated from the specific dissipation rate, a quantity defined as the ratio of the heat transfer rate to the difference in inlet temperature. The new blocks are composite components built on the new fundamental components `Simple Heat Exchanger Interface (G)`, `Simple Heat Exchanger Interface (TL)`, and `Specific Dissipation Heat Transfer`.

Pipe (TL) Block with Variable Elevation: Specify pipe elevation gain that varies during simulation

Model a thermal liquid pipe with a time-varying slope. The `Pipe (TL)` block from the **Thermal Liquid > Pipes & Fittings** library provides a new variant for this purpose. Change the block variant to specify the elevation gain from inlet to outlet as a variable input. Right-click the block and, from the **Simscape > Block Choices** menu, select `Variable elevation`. The block exposes a physical signal input port for the elevation gain signal.

Actuators and Cylinders with Configurable Hard Stops: Enforce motion limits with numerically smooth hard stops for faster simulation

Enforce the motion limits of actuators and cylinders using numerically smooth hard stops. The new hard stops have no zero crossings and are a suitable choice when simulation speed is of concern. They are available in actuators and cylinders of all types:

isothermal liquid, thermal liquid, and multi-fluid. Use the **Hard stop model** block parameter to select a hard-stop model. Options include:

- Stiffness and damping applied smoothly through transition region—
Scale the magnitude of the contact force from zero to its full value over a specified transition length. The scaling is polynomial in nature. The polynomial scaling function is numerically smooth and it produces no zero crossings of any kind.
- Full stiffness and damping applied at bounds, undamped rebound—
Apply the full value of the calculated contact force when the hard-stop location is breached. The contact force is a mix of spring and damping forces during penetration and a spring force—without a damping component—during rebound. No smoothing is applied.
- Full stiffness and damping applied at bounds, damped rebound—
Apply the full value of the calculated contact force when the hard-stop location is breached. The contact force is a mix of spring and damping forces during both penetration and rebound. No smoothing is applied. This is the hard-stop model used in previous software versions.

The new hard-stop models are available in the following blocks. In the Hydraulics (Isothermal) library:

- Double-Acting Hydraulic Cylinder
- Single-Acting Hydraulic Cylinder
- Double-Acting Rotary Actuator
- Single-Acting Rotary Actuator

In the Thermal Liquid library:

- Double-Acting Actuator (TL)
- Single-Acting Actuator (TL)

In the Fluid Network Interfaces library:

- Double-Acting Actuator (IL-G)
- Double-Acting Actuator (TL-G)

R2017a

Version: 2.2

New Features

Bug Fixes

Characteristic Curve Visualization: View the performance, efficiency, and loss curves for hydraulic pump and motor blocks

You can now plot a variety of characteristic curves from the Fixed-Displacement Pump and Fixed-Displacement Motor blocks, found in the **Hydraulics (Isothermal) > Pumps and Motors** library.

The characteristic curves include performance plots that show how power and flow rate vary with the pressure difference sustained between the ports. They include also efficiency and loss plots that show how the volumetric and mechanical efficiencies and losses vary with the shaft angular speed.

The performance plots are based on simulation data. The efficiency and loss plots are based on the analytical parameters or tabular data specified in the block dialog box. Use the efficiency and loss curves to check your input data—for example, to catch data-entry errors prior to simulation.

You can generate the characteristic curves from the block context-sensitive menu by selecting **Fluids > Plot Characteristic**. This menu option opens a model harness that you can simulate without affecting the source model. Follow the steps described in the model harness to generate the characteristic curves.

For more information, see Pump and Motor Characteristic Curves.

Multi-Fluid Actuators: Model power generation using multiple working fluids

Model a double-acting actuator with two types of working fluid, one being a gas and the other a hydraulic (isothermal) or thermal liquid, using the Double-Acting Actuator (IL-G) and Double-Acting Actuator (TL-G) blocks from the new **Fluid Network Interfaces > Actuators** library. The blocks serve as interfaces between the different fluid domains and the mechanical translational domain.

Hydraulic Directional Valves with Asymmetric Port Areas: Specify unique area characteristics for each port

Model a hydraulic directional valve with different flow areas between its ports. You can specify the properties of each flow path separately as a function of control member displacement. Valve blocks with asymmetric port areas include 3-Way Directional Valve

and 4-Way Directional Valve. You can find the blocks in the **Hydraulic (Isothermal) > Valves > Directional Valves** library. Set the **Area characteristics** parameter in the **Basic Parameters** tab to `Different` for each flow path to specify the properties of each flow path separately.

Run-Time Parameters: Speed up simulation tasks and modify component parameter values without regenerating C code

Simscape Fluids software now supports run-time parameters. You can configure most numerical block parameters as `Compile-time` (default) or `Run-time` using a drop-down list that appears beside configurable parameters. The figure shows the run-time drop-down list in a 4-Way Directional Valve (TL) block dialog box. All parameters are by default `Compile-time`.

| Parameters | Valve Opening Offsets | | |
|------------------------|--------------------------------|--------------------------------|---|
| Between ports P and A: | <input type="text" value="0"/> | <input type="text" value="m"/> | <input type="text" value="Compile-time"/> |
| Between ports B and T: | <input type="text" value="0"/> | <input type="text" value="m"/> | <input type="text" value="Run-time"/> |
| Between ports P and B: | <input type="text" value="0"/> | <input type="text" value="m"/> | <input type="text" value="Compile-time"/> |
| Between ports A and T: | <input type="text" value="0"/> | <input type="text" value="m"/> | <input type="text" value="Compile-time"/> |

`Compile-time` parameters update in value only when you recompile the model. Use them when performing tasks that rely on inlined parameters such as model optimization. `Run-time` parameters update in value without the need for extra compilations. Use them when tuning parameter values in Fast Restart mode or when simulating models that rely at least in part on generated C code.

To set a parameter as `Run-time` from the block dialog box, you must configure your Simscape preferences. Open the MATLAB® Preferences window, select the **Simscape** node, and check the **Show run-time parameter settings** check box. Parameters without a run-time option or with a run-time option that is inactive (i.e., “grayed out”) cannot be configured.

For more information about Simscape run-time parameters, see About Simscape Run-Time Parameters.

Hydraulic Tank Block Updates

Three hydraulic tank blocks have merged into a single block named Tank. The merged blocks include Variable Head Tank, Variable Head Two-Arm Tank, and Variable Head Three-Arm Tank. The new Tank block provides three Simscape variants corresponding to the merged blocks—these differing in their numbers of ports, which ranged from one to three.

You can select a Simscape variant from the context-sensitive menu of the block. Right-click the block to open the menu and select **Simscape > Block Choices** to pick a variant. The `One inlet` variant corresponds to the old Variable Head Tank block, the `Two inlets` variant to the old Variable Head Two-Arm Tank block, and the `Three inlets` variant to the old Variable Head Three-Arm Tank block.

Hydraulic Ball Valve Block Updates

Two hydraulic ball valve blocks have merged into a single block named Ball Valve. The merged blocks include Ball Valve and Ball Valve with Conical Seat. The updated Ball Valve block provides two block parameterizations corresponding to the merged blocks—these differing in their valve seat geometries.

Use the **Valve seat specification** parameter to select a valve seat geometry. The `Sharp-edged` parameterization corresponds to the previous version of the Ball Valve block. The `Conical` parameterization corresponds to the previous version of the Ball Valve with Conical Seat block.

R2016b

Version: 2.1

New Features

Bug Fixes

Numerical Enhancements in Hydraulic Pump and Motor Blocks: Transition robustly between pumping and motoring regimes

Pump and motor blocks from the Hydraulics (Isothermal) library support new operation modes. The updated blocks can each operate as forward pumps, reverse pumps, forward motors, and reverse motors. The pressure difference between the hydraulic ports and the rotational velocity at the mechanical rotational port determine the actual operation mode. Hyperbolic \tanh functions smooth the transitions between the modes.

Loss Parameterizations in Hydraulic Pump and Motor Blocks: Specify variable losses and efficiencies using physical signals or lookup tables

Pump and motor blocks from the Hydraulics (Isothermal) library provide new ways of accounting for power losses. You can now specify mechanical and volumetric efficiencies and losses using physical signals or 2D lookup tables. To change the specification method, you must change the block variant using the block context-sensitive menu. Right-click the block and, from the **Simscape > Block choices** menu, select the appropriate option. The blocks with the new variants are:

- Fixed-Displacement Motor
- Fixed-Displacement Pump
- Variable-Displacement Motor
- Variable-Displacement Pump

Interface (TL-IL) Block: Connect thermal liquid and isothermal liquid networks

The Fluid Network Interfaces library provides a new block, Interface (TL-IL). Use the new block to connect a thermal liquid network to a hydraulic (isothermal liquid) network. The block matches the pressure and mass flow rates at the interface while keeping the network fluid properties separate. Heat transfer occurs between the thermal liquid and the interface but not between the interface and the hydraulic fluid.

Mass Flow Rate Measurements: Log and sense mass flow rates through pump and motor blocks

Pump and motor blocks from the Hydraulics (Isothermal) library now use mass flow rate as an explicit variable. You can sense the new variable using the updated Hydraulic Flow

Rate Sensor block, which now senses mass flow rates directly. You can also use Simscape logging to access the mass flow rate data for a hydraulic node.

Hydraulics (Isothermal) Library: Motor blocks combined and renamed

The Fixed-Displacement Motor (External Efficiencies) block has been combined with the Hydraulic Motor block and renamed Fixed-Displacement Motor. The updated block comprises three block variants that preserve and expand the functionality of the original blocks. To access the block variants, right-click the block and select **Simscape > Block choices**.

R2016a

Version: 2.0

New Features

Bug Fixes

SimHydraulics renamed to Simscape Fluids

The SimHydraulics® product is now named Simscape Fluids. The product library is located in the Simscape node of the Simulink® library browser under the name Fluids. You can open the product library at the MATLAB command prompt using the new `SimscapeFluids_lib` command.

Thermal Liquid Library: Model systems containing liquids whose properties vary with temperature

A new Thermal Liquid library enables you to capture the effects of temperature change on liquid properties. You can use the Thermal Liquid library to model any liquid system where thermal effects are important. Applications include power transmission systems such as hydraulic actuators, liquid transport systems such as oil pipelines, and heating and cooling systems such as HVAC units.

The new library provides specialized components not found in the Simscape Foundation Thermal Liquid library. These include detailed models of actuators, accumulators, valves, pumps, and motors. A separate library named Fluid Network Interfaces enables you to model heat exchange between separate fluid subsystems. The new blocks are based on the existing Simscape Thermal Liquid domain.

For a tutorial showing how to model a simple thermal liquid system, see [Model a Thermal Liquid Pipeline](#).

Thermal Liquid Examples

The following featured examples show some applications of the new Thermal Liquid library:

- Engine Cooling System
- Hydraulic Oil System with Thermal Control
- Reciprocal Actuator with Differential Cylinders

R2015b

Version: 1.17

New Features

Bug Fixes

Pneumo-Hydraulic Actuator block with two mechanical ports

The Pneumo-Hydraulic Actuator block can now have either one or two mechanical translational ports:

- Use the variant with one mechanical port to model just the load on the piston. In this case, the cylinder is assumed to be grounded.
- Use the variant with two mechanical ports to model the load on the actuator cylinder, as well as the piston. This variant also lets you include liquid compressibility on the hydraulic side of the actuator.

By default, the block has one mechanical port. To switch to the two-port variant, right-click on the block in your model and then, from the context menu, select **Simscape > Block choices > Two mechanical ports**. The block icon displays the additional port, and the block dialog changes to include the additional parameters on the **Hydraulic Side** tab.

R2015a

Version: 1.16

New Features

Bug Fixes

Variable-Displacement Hydraulic Machine (External Efficiencies) block

The new Variable-Displacement Hydraulic Machine (External Efficiencies) block in the Pumps and Motors library represents a reversible, variable positive-displacement hydraulic machine with volumetric and mechanical efficiencies provided externally to the block through physical signal ports EV and EM, respectively. The machine displacement is controlled by the signal provided through the physical signal port C. The block can work as a pump or a motor, depending on the direction of mechanical and hydraulic power flow. To ensure continuity at the instance when the machine switches its operational mode, the block implements a small transition region, defined by the power threshold value. This transition region helps avoid a discontinuity and improve numerical convergence.

Valve opening dynamics in directional and pressure control valves

The following blocks now have an additional parameter that lets you consider valve opening dynamics:

- Check Valve
- Pilot-Operated Check Valve
- Hydraulically Operated Remote Control Valve
- Shuttle Valve
- Pressure Compensator
- Pressure Reducing 3-Way Valve
- Pressure Reducing Valve
- Pressure Relief Valve

The default block behavior is unchanged, that is, the valve sets its opening area directly as a function of pressure. However, as the area changes instantaneously, so does the flow equation, often by many orders of magnitude. Adding valve opening dynamics provides continuous behavior that is more physically realistic, and is particularly helpful in situations with rapid valve opening and closing.

If you set the new **Opening dynamics** parameter to `Include valve opening dynamics`, two additional parameters become available:

- **Opening time constant** — The time constant for the first order response of the valve opening.

-
- **Initial area** — The initial opening area of the valve.

The orifice passage area depending on pressure $A(p)$ in the block equations then becomes the steady-state area, calculated exactly as before, and the instantaneous orifice passage area is calculated as

$$area.der = (steady-state\ area - area) / opening\ time\ constant,$$

with $area = initial\ area$ at $t = 0$.

Use this feature in hydraulic simulations with the local solver for real-time simulation. This feature is also helpful if you are interested in valve opening dynamics in variable step simulations.

Accumulator blocks with improved hard stops

The Gas-Charged Accumulator and Spring-Loaded Accumulator blocks are each equipped with two hard stops, used to restrict the fluid volume between zero and the full fluid chamber capacity. In R2014b, these hard stops were modeled as absolutely plastic. As a result, the fluid volume could drift below zero or above fluid chamber capacity in some situations.

Starting in R2015a, the hard stop model in the accumulator blocks includes both a stiffness term and a damping term to prevent the nonphysical values from occurring. When the hard stops are modeled with finite stiffness and damping, it is still possible for the fluid volume to become slightly negative or slightly greater than the fluid chamber capacity. This represents the deflection in the hard stops.

As a result of these changes, both blocks now have a new parameter, **Hard-stop stiffness coefficient**, which accounts for the stiffness term in the hard-stop equations. The old parameter **Penetration coefficient** has been renamed to **Hard-stop damping coefficient**, and some other block parameters have been renamed for clarity. See the block reference pages for details.

When you upgrade from R2014b, the blocks in existing models automatically assume a value of zero for the **Hard-stop stiffness coefficient** parameter value to preserve the existing behavior. When you upgrade from R2014a or earlier, the blocks in existing models automatically assume the new default values for the **Hard-stop stiffness coefficient** and **Hard-stop damping coefficient** parameters.

New examples

The following example has been introduced in this version:

- Hydraulic System with Priority Valve

R2014b

Version: 1.15

New Features

Bug Fixes

Flow Divider-Combiner block

The new Flow Divider-Combiner block in the Flow Control Valves library models a valve that divides the direct flow (incoming to port P) between two outlets, and also maintains a specified proportion between return flows through ports A and B in the total flow rate through port P. In other words, the valve works in two distinctive modes: flow divider for direct flow and flow combiner for reverse flow. The existing Flow Divider block, also available in the Flow Control Valves library, cannot be used as a flow combiner.

Variable Orifice Between Round Holes block

The new Variable Orifice Between Round Holes block in the Orifices library simulates a variable orifice created by two interacting round holes, which can be of different diameters. One hole is located in the sleeve, while the other is drilled in the case, with the sleeve sliding along the case. Use this block in cartridge valve models.

R2014a

Version: 1.14

New Features

Bug Fixes

Compatibility Considerations

Removal of laminar-turbulent zero-crossings in flow rate equations

Flow rate equations used in orifices, valves, local resistances, and low-pressure blocks have been modified so that they no longer produce zero-crossings upon transition between the laminar and turbulent regimes during simulation. This enhancement increases simulation efficiency for hydraulic models. Numerical simulation results are essentially the same.

Improvement of mass conservation for cylinders with fluid compressibility

The schematics of the cylinder and rotary actuator blocks no longer include the Hydraulic Piston Chamber block. Instead, they are now using the updated hydro-mechanical converter blocks from the Simscape Foundation library, which let you account for fluid compressibility inside the converter block. For more information see the Simscape Release Notes item, Hydro-mechanical converter blocks with fluid compressibility option.

Gate Valve equations change

The equations used to calculate the instantaneous area of the valve opening have changed, to increase the fidelity of simulation. The area is now computed with the same equation for the whole working range, $0 < h \leq 2D$:

$$A(h) = D^2 \cdot (\alpha / 2 - \sin(2\alpha) / 4).$$

The angle α is computed as $\alpha = \arccos(1 - h / D)$ for the first half of the working range, $0 < h \leq D$, and as $\alpha = \arccos(h / D - 1)$ for the second half, $D < h \leq 2D$.

Compatibility Considerations

Numerical simulation results for legacy models containing this block may change slightly because of the change in the block equations.

R2013b

Version: 1.13

New Features

Bug Fixes

Cylinder Cushion block

The new Cylinder Cushion block in the Hydraulic Cylinders library models a hydraulic cylinder cushion, the device that decelerates the cylinder rod as it approaches the end of stroke by restricting flow rate leaving the cylinder chamber.

Pressure-Compensated 3-Way Flow Control Valve block

The new Pressure-Compensated 3-Way Flow Control Valve block in the Flow Control Valves library simulates a pressure-compensated 3-way flow control valve. The valve includes a variable orifice and a normally closed pressure-control valve, connected in parallel with the orifice. The purpose of the pressure-control valve is to maintain a preset pressure differential across the orifice by diverting some flow from port A to tank (through port R) if pressure differential exceeds the setting.

Pressure Reducing 3-Way Valve block

The new Pressure Reducing 3-Way Valve block in the Pressure Control Valves library simulates a pressure reducing 3-way valve, sometimes also referred to as a pressure reducing/relieving valve. The valve reduces inlet pressure to a preset value, similar to a conventional pressure-reducing valve, but, additionally, starts working as a pressure-relief valve if the pressure continues to rise.

Nominal fluid density parameter for pump and motor blocks

The **Nominal fluid density** parameter lets you specify a value for fluid density, to allow more flexibility and accuracy in modeling the working fluid. Previously, only fluid viscosity was adjustable. The parameter has been added for the following blocks in the Pumps and Motors library:

- Variable-Displacement Pressure-Compensated Pump
- Variable-Displacement Pump
- Variable-Displacement Motor
- Fixed-Displacement Pump
- Hydraulic Motor

R2013a

Version: 1.12

New Features

Bug Fixes

Flow Divider block

The Flow Divider block simulates a hydraulic two-path flow divider, which consists of a spring-centered spool installed in a case. The flow from the source enters the valve and is split into two paths. Each path contains a fixed orifice and a variable orifice. The fixed orifices must be precisely matched to divide flow in equal parts, or arranged in a certain proportion if unequal division is required. The purpose of variable orifices is to maintain a constant pressure drop across the fixed orifices, regardless of pressure fluctuations at valve outlets. The load increase on any outlet causes the pressure drop across the spool (and across fixed orifices) to change, and thus shift the spool. As a result, the passage areas of variable orifices change until the pressure drop values across the fixed orifices even out.

The Hydraulic System with Flow Divider example illustrates using a Flow Divider block to split the flow equally between two consumers, represented by Orifice with Variable Area Slot blocks.

Fixed Orifice with Fluid Inertia block

The Fixed Orifice with Fluid Inertia block models a hydraulic fixed orifice that accounts for the fluid inertia, in addition to the static pressure loss. Fluid inertia plays a noticeable role in orifices with large ratio of orifice length to the orifice hydraulic diameter (L / D_H), or in sharp-edged short orifices when the rate of change of flow rate (fluid acceleration) is relatively large. The model accounts for the laminar and turbulent flow regimes by monitoring the Reynolds number (Re) and comparing its value with the critical Reynolds number (Re_{cr}). The transition between laminar and turbulent regimes is assumed to be sharp and taking place exactly at $Re=Re_{cr}$.

Double-Acting Servo Cylinder block

The Double-Acting Servo Cylinder block models a hydraulic double-acting servo cylinder implemented as a spring-centered plunger. Changing pressure at ports A and B shifts the plunger from neutral position proportionally to the pressure differential. Use the servo cylinder for control purposes.

Partially Filled Vertical Pipe LP block

The Partially Filled Vertical Pipe LP block models a vertical pipe connecting two tanks, with the possibility that the top tank gets emptied, and therefore the top part of the pipe

can be exposed. The fluid level in the pipe then settles at some intermediate position depending on pressures at both ports. The block models pipes with circular and noncircular cross sections. The block accounts for friction losses, variable fluid level in the pipe, and resulting variable heads at the ports.

Spool Orifice Hydraulic Force block that now supports round hole orifices

The Spool Orifice Hydraulic Force block simulates the steady-state axial hydraulic force exerted on the spool by fluid flowing through the orifice. In previous releases, the orifice was supposed to be rectangular. Now you have two parameterization options:

- A rectangular slot
- A round hole, or a set of round holes

The spool is assumed to be sharp-edged. The orifice width, or diameter, must be considerably larger than the radial clearance between the spool and the sleeve.

Improved conservation of mass for cylinders with fluid compressibility

The four cylinder blocks that account for fluid compressibility have been changed to include custom translational or rotational hydro-mechanical converters, instead of the corresponding standard blocks from the Simscape Foundation library. The custom hydro-mechanical converters take into account pressure-induced density variations to give increased accuracy. The affected blocks are:

- Double-Acting Hydraulic Cylinder
- Double-Acting Rotary Actuator
- Single-Acting Hydraulic Cylinder
- Single-Acting Rotary Actuator

New examples

The following example has been introduced in this version:

- Hydraulic System with Flow Divider

R2012b

Version: 1.11

New Features

Bug Fixes

Journal Bearing Pressure-Fed block

The new Journal Bearing Pressure-Fed block in the Orifices library simulates the hydraulic portion of a pressure-fed journal bearing. Connections A and B are hydraulic conserving ports associated with the bearing inlet and outlet, respectively. The journal radial displacement, which controls the bearing eccentricity, is imported through the physical signal port J. The flow regime is assumed to be laminar due to small clearances. Use this block in lubrication system simulation to assess the flow consumption through the pressure-fed journal bearing.

Fixed Orifice Empirical block

The new Fixed Orifice Empirical block in the Orifices library models a fixed orifice in hydraulic systems with data obtained from experimental testing. The data required for characterization is the set of pressure differentials across the orifice, together with associated flow rates determined for a particular fluid and temperature. The block operates as a one-dimensional table lookup, with three interpolation and two extrapolation methods.

Fixed-Displacement Motor (External Efficiencies) block

The new Fixed-Displacement Motor (External Efficiencies) block in the Pumps and Motors library represents a fixed-displacement hydraulic motor with both mechanical and volumetric efficiencies provided through the external physical signal ports. Hydraulic losses are implemented as a leakage between hydraulic ports, while mechanical losses are introduced through the friction imposed on the driving shaft. Both the leakage and the friction are determined by the efficiency values.

Pneumo-Hydraulic Actuator block

The new Pneumo-Hydraulic Actuator block in the Cylinders library simulates a pneumo-hydraulic actuator, implemented as a double-acting cylinder with one side connected to a hydraulic power supply and another side operated by pneumatic power. The hydraulic part of the model accounts only for fluid consumption associated with the piston velocity. The pneumatic part of the model is built with the ideal gas relationships. To simulate the limit on the piston motion, the hard stop is included in the model. The piston effective area is constant.

The model is suitable for building pneumo-hydraulic or hydro-pneumatic pumps, intensifiers, and similar devices. You can simulate piston loading (such as inertia,

springs, friction) by modeling the load externally and connecting it to port L. Similarly, simulate the heat exchange with the environment through the external thermal port E, which corresponds to the gas in the chamber. Use blocks from the Simscape Foundation library, such as Convective Heat Transfer, Conductive Heat Transfer, Thermal Mass, and so on, depending on the actual system configuration.

Counterbalance Valve and Hydraulically Operated Remote Control Valve blocks

Two new blocks extend the valve modeling capabilities:

- The Counterbalance Valve block in the Flow Control Valves library models an internally-externally piloted counterbalance valve. The purpose of a counterbalance valve is to control an overriding or suspended load by creating additional pressure in the discharge line of a hydraulic actuator. The block is essentially a data-sheet-based model that lets you characterize the valve by data usually provided in manufacturer catalogs or data sheets.
- The Hydraulically Operated Remote Control Valve block in the Directional Valves library represents a remote control valve where the valve control member (spool, poppet, and so on) can be shifted from its initial position after pressure at the pilot port exceeds the cracking pressure limit. The valve passage area is directly proportional to pilot pressure. The model covers both normally closed and normally open valve configurations.

New examples

The following example has been introduced in this version:

- Hydraulic System with Counterbalance Valve

R2012a

Version: 1.10.1

Bug Fixes

R2011b

Version: 1.10

New Features

New Gate Valve Block

The new Gate Valve block in the Flow Control Valves library models a valve consisting of a round orifice in the valve housing and a flat gate, which moves perpendicular to the orifice axis. The orifice in the gate has the same diameter as the orifice in the housing. As the gate moves, it opens or closes the valve passage. The flow rate through the valve is proportional to the orifice opening and to the pressure differential across the orifice.

Swash Plate Block Enhancement

The Swash Plate block in the Pumps and Motors library now has the **Piston offset from the plate** parameter, which lets you specify the offset between the piston tip and the plate. The default value is 0, which corresponds to the block implementation in the previous version.

Segmented Pipe Block Enhancement

Additional parameters in the Segmented Pipeline block let you specify the initial condition for pressure inside the pipe segments. You have two options:

- The same initial pressure for all nodes — The initial pressure in all pipe segments is the same, and is specified by the **Initial pressure** parameter value. This is the default.
- Custom — Lets you specify initial pressure individually for each pipe segment, by using the **Initial pressure vector** parameter. The vector size must be equal to the number of pipe segments, defined by the **Number of segments** parameter value.

R2011a

Version: 1.9

New Features

Bug Fixes

New Swash Plate Block

The new Swash Plate block in the Pumps and Motors library models a swash plate mechanism used in axial-piston machines to convert translational motion of a piston into rotational motion of a drive shaft. For details, see the block reference page and the new Hydraulic Axial-Piston Pump with Load-Sensing and Pressure-Limiting Control (sh_hydraulic_axial_piston_pump) demo.

New Porting Plate Variable Orifice Block

The new Porting Plate Variable Orifice block in the Pumps and Motors library models a variable orifice located between the piston chamber and a crescent-shaped slot on a porting plate in hydraulic axial-piston machines. For details, see the block reference page and the new Hydraulic Axial-Piston Pump with Load-Sensing and Pressure-Limiting Control (sh_hydraulic_axial_piston_pump) demo.

New Angle Sensor Block

The new Angle Sensor block in the Pumps and Motors library models an ideal angle sensor with measuring range from zero to 360 degrees. With the sensor probe connected to a mechanical rotational port, the output is a value between 0 and 2π , regardless of the number of revolutions performed by the probe and direction of rotation. For an example of block usage, see the new Hydraulic Axial-Piston Pump with Load-Sensing and Pressure-Limiting Control (sh_hydraulic_axial_piston_pump) demo.

Changes to SimHydraulics Demos

The following demo has been added in Version 1.9:

| Demo Name | Description |
|-----------|-------------|
|-----------|-------------|

| | |
|---|---|
| <p>Hydraulic Axial-Piston Pump with Load-Sensing and Pressure-Limiting Control (sh_hydraulic_axial_piston_pump)</p> | <p>The demo models a test rig designed to investigate interaction between an axial-piston pump and a typical control unit, simultaneously performing the load-sensing and pressure-limiting functions. To assure required accuracy, the model of the pump must account for such features as interaction between pistons, swash plate, and porting plate, which makes it necessary to build a detailed pump model.</p> |
|---|---|

R2010b

Version: 1.8

New Features

Bug Fixes

New Jet Pump Block

The new Jet Pump block in the Pumps and Motors library models a jet liquid-liquid pump operating with identical primary and secondary fluids containing no gas. For details, see the block reference page and the new Well Jet Pump (`sh_well_jet_pump`) demo.

Hydraulic Pipeline Block Enhancement

The Hydraulic Pipeline block now contains an additional parameter that lets you set the initial pressure inside the pipe at the start of simulation. See the block reference page for details.

Changes to SimHydraulics Demos

The following demos have been added in Version 1.8:

| Demo Name | Description |
|--|--|
| Rotating Hydraulic Actuator (<code>sh_rotating_hydraulic_actuator</code>) | Simulates a typical hydraulic cylinder actuator used to operate friction clutches, brakes and other devices installed on rotating shafts. |
| Well Jet Pump (<code>sh_well_jet_pump</code>) | Simulates a well jet pump installation, consisting of a surface-mounted centrifugal pump and a jet pump installed in the well below water level. |

R2010a

Version: 1.7

New Features

Bug Fixes

Compatibility Considerations

Simplified Blocks for Real-Time Simulation

The following new blocks implement simplified models that reproduce only basic functionality in exchange for better numerical efficiency:

- Single-Acting Hydraulic Cylinder (Simple) block represents a simplified version of a single-acting hydraulic cylinder. The model assumes fluid compressibility, friction, and leakages to be negligible. The hard stops are assumed to be fully inelastic, to eliminate any possible oscillations at the end of the stroke.
- Double-Acting Hydraulic Cylinder (Simple) block represents a simplified version of a double-acting hydraulic cylinder. The model assumes fluid compressibility, friction, and leakages to be negligible. The hard stops are assumed to be fully inelastic, to eliminate any possible oscillations at the end of the stroke.
- 4-Way Ideal Valve block represents a 4-way critically-centered valve. Initial openings of all orifices are set to 0, which significantly simplifies the model.
- Valve Actuator block represents a simplified version of a valve actuator, built as a first-order lag.

Use these blocks for real-time and HIL (hardware-in-the-loop) simulation, if such simplifications are acceptable.

Low-Pressure Blocks with Variable Elevations

Additional blocks in the Low-Pressure Blocks library incorporate elevation information and let you specify elevations as input signals, rather than as block parameters:

- Resistive Pipe LP with Variable Elevation block represents a hydraulic pipeline which accounts for friction losses and port elevations.
- Hydraulic Pipe LP with Variable Elevation block represents a hydraulic pipeline with resistive, fluid compressibility, and elevation properties.

Use these blocks for low-pressure system simulation in which the pipe ends change their positions with respect to the reference plane.

Cartridge Valve Modeling Blocks

Two new blocks extend the cartridge valve modeling capabilities:

-
- Cartridge Valve Insert with Conical Seat block represents an insert of a hydraulic cartridge valve consisting of a poppet interacting with the conical seat.
 - Hydraulic 4-Port Cartridge Valve Actuator block represents double-acting hydraulic valve actuator driven by four pressures. Use this block as a pilot actuator for cartridge valves, as well as pilot-operated pressure and control valves, in applications where all the forces, except spring and pressure forces, and flow consumption can be neglected.

There are also additional parameters in the Hydraulic Cartridge Valve Actuator block that account for initial conditions and dynamic properties of the model. See the block reference page for details.

Lubrication System Modeling Blocks

The following blocks have been added to facilitate modeling lubrication systems:

- Centrifugal Force in Rotating Cylinder block simulates centrifugal forces exerted by fluid on a piston if the cylinder rotates about its symmetry axis. Such cylinders are used in control mechanisms of various friction clutches, brakes, square-jaw positive clutches, dog clutches, and so on. No inertial effects are considered in the model. In other words, the angular velocity is assumed to be constant or changing at very low speed.
- Rotating Pipe block models a hydraulic pipeline represented as a short bore drilled through a shaft at some angle to its axis, or as a short pipe that connects actuator or bearings, mounted on the shaft, with the channel inside the shaft. Such connections are typical for lubrication systems and for hydraulically-operated clutches and mechanisms. The shaft angular velocity is assumed to be constant or changing at very low speed.

Centrifugal Pump Enhancement

The Centrifugal Pump block now contains additional parameters that let you simulate operation at zero angular velocity. See the block reference page for details.

Initial Piston Position in the Single-Acting Hydraulic Cylinder Block

The **Piston initial position** parameter in the block dialog box has been renamed to **Initial distance between piston and cap**, and the way it is used in the block output has been changed.

In previous versions, the **Piston initial position** parameter let you specify the distance that the piston is extended at the beginning of simulation by setting the piston initial position to any point within its stroke, but this value was not included in calculating the rod displacement. In other words, the rod displacement output at the block's physical signal port was with respect to the initial piston position.

In the current version, the **Initial distance between piston and cap** parameter value is included in calculating the rod displacement output by the block:

$$x_{pst} = x_0 + x_p$$

where

| | |
|-----------|---|
| x_{pst} | Rod displacement output by the physical signal port |
| x_0 | Initial distance between piston and cap |
| x_p | Rod displacement with respect to its initial position |

For details, see the block reference page.

Compatibility Considerations

The block output changes because of the new way it calculates rod displacement. It used to start out at zero but now starts out at the initial position. If you have used this block with nonzero initial position in your models, the block output will differ by this value:

$$x_{new} = x_0 + x_{old}$$

where

| | |
|-----------|---|
| x_{new} | Rod displacement output by the physical signal port in the current version |
| x_{old} | Rod displacement output by the physical signal port in the previous version |
| x_0 | Piston initial position value |

Changes to SimHydraulics Demos

The following demos have been added in Version 1.7:

| Demo Name | Description |
|-----------|-------------|
|-----------|-------------|

| | |
|---|--|
| <p>Diesel Engine In-Line Injection System (sh_diesel_engine_in_line_injection_system)</p> | <p>Simulates an in-line multi-element injection system. The objective of the simulation is to investigate the entire system operation.</p> |
| <p>Fuel Supply System with Variable Elevation (sh_fuel_supply_system_with_variable_elevations)</p> | <p>Simulates a three-tank fuel supply system where side tanks periodically change elevations during the simulation cycle.</p> |
| <p>Hydraulic Actuation System with Cartridge Valves (sh_actuation_system_cartridge_valve)</p> | <p>Simulates a complex actuation system equipped with cartridge valves.</p> |
| <p>Hydraulic Closed-Loop Actuator with Fixed-Step Integration (sh_hydraulic_closed_loop_actuator_fixed_step)</p> | <p>Represents two versions of the same closed-loop hydraulic actuator. In the second version, standard SimHydraulics blocks are replaced with their simplified versions and the model is optimized for fixed-step integration.</p> |

R2009b

Version: 1.6

New Features

Bug Fixes

Additional 4-Way and 6-Way Directional Valve Configurations

Nine 4-way directional valve blocks and one 6-way directional valve block have been added to the Directional Valves library, and the original 4-Way Directional Valve block has been modified, to enable additional valve configurations. For more information, see Modeling Directional Valves, as well as individual block reference pages.

Additional Low-Pressure Blocks

The following blocks have been added to the Low-Pressure Blocks library:

- Variable Head Two-Arm Tank block represents a tank with constant pressurization and volume-dependent fluid level. The tank has two hydraulic ports and a physical signal port, which exports the volume of fluid in the tank.
- Variable Head Three-Arm Tank block represents a tank with constant pressurization and volume-dependent fluid level. The tank has three hydraulic ports and a physical signal port, which exports the volume of fluid in the tank.

Both blocks account for the fluid level change caused by the volume variation, as well as for pressure loss in the connecting pipes that can be caused by a filter, fittings, or some other local resistance. You can specify pipeline diameter, pressure loss coefficient, and elevation information for each hydraulic port separately.

New Ball Valve with Conical Seat Block

The new Ball Valve with Conical Seat block in the Flow Control Valves library models a ball valve created by a spherical ball and a conical seat. The valve is characterized by the ball diameter, cone angle, and orifice diameter.

R2009a

Version: 1.5

New Features

Bug Fixes

New Low-Pressure Blocks Library

The Low-Pressure Blocks library, added in this release, contains five new blocks that incorporate elevation information:

- Constant Head Tank block represents a tank where pressurization and fluid level remain constant regardless of volume change. The block accounts for the fluid level elevation with respect to the tank bottom, as well as for pressure loss in the connecting pipe that can be caused by a filter, fittings, or some other local resistance.
- Variable Head Tank block represents a tank with constant pressurization and volume-dependent fluid level. The block accounts for the fluid level change caused by the volume variation, as well as for pressure loss in the connecting pipe that can be caused by a filter, fittings, or some other local resistance.
- Resistive Pipe LP block represents a hydraulic pipeline which accounts for friction losses and port elevations.
- Hydraulic Pipe LP block represents a hydraulic pipeline with resistive, fluid compressibility, and elevation properties.
- Segmented Pipe LP block represents a hydraulic pipeline with resistive, fluid inertia, fluid compressibility, and elevation properties.

These blocks enable additional applications, such as low-pressure fluid transportation system simulation.

Changes to SimHydraulics Demos

The following demos have been added in Version 1.5:

| Demo Name | Description |
|---|---|
| Water Supply System (sh_water_supply_system) | The water supply system modeled in the demo consists of three pumping stations located at 45, 25, and 30 m with respect to the reference plane, respectively. All three stations are expected to pump water in a tank located at 61 m. The objective of simulation is to determine steady-state flow rates and pressures. |

| | |
|--|--|
| <p>Fluid Transportation System with Three Tanks (sh_three_tanks)</p> | <p>The demo illustrates a classical problem of fluid transportation: to determine flow rates, pressures, and fluid volumes in a system built of three constant head tanks. The tanks are located at different elevations and connected with pipelines combined together in a common node. The pipelines are simulated with the Segmented Pipeline LP block, which accounts for hydraulic losses, fluid inertia, and the head due to different node elevations.</p> |
|--|--|

R2008b

Version: 1.4

New Features

Bug Fixes

Explicit Solvers Now Available for SimHydraulics Models

Using explicit solvers has been implemented for models that include Simscape and SimHydraulics blocks. For more information, see *Setting Up Solvers for Physical Models* in the Simscape documentation.

New Variable-Displacement Hydraulic Machine Block

The Variable-Displacement Hydraulic Machine block, able to work as a pump or a motor, enables modeling variable-efficiency machines based on manufacturer's data sheets. The machine displacement is controlled by the signal provided through the physical signal port C. The machine efficiency is simulated by implementing regime-dependable leakage and friction torque based on the experimentally established correlations between the machine efficiencies and pressure, angular velocity, and displacement.

Improved Usability of the 4-Way Directional Valve Block

The 4-Way Directional Valve block dialog box has been reorganized using tabs to improve usability. Use the **Initial openings** tab to set all the initial orifice openings. The **Basic parameters** tab contains the model parameterization options and the corresponding parameters. The parameters themselves have not changed.

Changes to SimHydraulics Demos

The following demos have been added in Version 1.4:

| Demo Name | Description |
|---|---|
| Hydraulic Drill-Ream Actuator (sh_drill_ream_actuator) | The actuator is intended to drive a machine tool working unit performing a sequence of three technological operations: coarse drilling, fine drilling, and reaming. The actuator speed is controlled by one of three pressure-compensated flow control valves metering out return flow from the cylinder. The selection of an appropriate flow control is performed by directional valves that are activated by a control unit. |

| | |
|--|---|
| <p>Front-Loader Actuation System (sh_front_loader_actuation_system)</p> | <p>The model shows a simplified version of an actuation system consisting of the lift and tilt cylinders. Each of the cylinders is controlled by an open center, 5-way, 3-position directional valve. The valves are connected in series through their unloading branch in such a way that the system pump is unloaded when both command levers are in neutral position. If either tilt or lift command is applied, the unloading path is closed.</p> |
| <p>Pipeline System with Centrifugal Pump (sh_pipeline_system_centrifugal_pump)</p> | <p>The demo represents a typical pipeline system with the centrifugal pump. The system is built of three manifolds connected with hoses. The combination of valves installed inside manifolds allows flow rate to be directed through different branches. The manifold models account for local resistances, elbows, and cylindrical channels.</p> |

Also, the Variable Volume Chamber Test Rig (sh_variable_chamber_test_rig) demo has been renamed to Variable Volume Piston Chamber Test Rig, and all the Variable Volume Chamber blocks in it have been replaced with Piston Chamber blocks.

R2008a

Version: 1.3

New Features

Bug Fixes

Trimming Now Available for SimHydraulics Models

Finding and managing operating points by trimming has been implemented for models that include Simscape and SimHydraulics blocks. Simulink Control Design™ product is required for using this functionality. For more information, see *Trimming Simscape Models* in the Simscape documentation.

New Cartridge Valve Insert and Hydraulic Cartridge Valve Actuator Blocks

Two new blocks facilitate modeling cartridge valves:

- Cartridge Valve Insert block in the Directional Valves library represents an insert of a hydraulic cartridge valve consisting of a poppet interacting with the sleeve seat. The poppet position is determined by pressures at ports A, B, and X and force of the spring. This is a structural model based on a Variable Orifice block and a Hydraulic Cartridge Valve Actuator block, described below.
- Hydraulic Cartridge Valve Actuator block in the Valve Actuators library represents a double-acting hydraulic valve actuator driven by three pressures. Use this block as a pilot actuator for cartridge valves, as well as pilot-operated pressure and control valves in applications where all the forces, except spring and pressure forces, and flow consumption can be neglected.

Additional Configurations for the Centrifugal Pump Block

The Centrifugal Pump block represents a centrifugal pump of any type as a data-sheet-based model. Depending on data listed in the manufacturer's catalogs or data sheets for your particular pump, you can now choose one of the following model parameterization options:

- *By approximating polynomial* — Provide values for the polynomial coefficients. These values can be determined analytically or experimentally, depending on the data available. This is the default method, equivalent to the implementation available in the previous release.
- *By two 1D characteristics: P-Q and N-Q* — Provide tabulated data of pressure differential and brake power versus pump delivery characteristics. The pressure differential and brake power are determined by one-dimensional table lookup. You have a choice of three interpolation methods and two extrapolation methods.

-
- By two 2D characteristics: P-Q-W and N-Q-W— Provide tabulated data of pressure differential and brake power versus pump delivery characteristics at different angular velocities. The pressure differential and brake power are determined by two-dimensional table lookup. You have a choice of three interpolation methods and two extrapolation methods.

Additional Fluids Available in the Hydraulic Fluid Block

The following predefined fluids have been added to the Hydraulic Fluid block:

- ISO VG 22 (ESSO UNIVIS N 22)
- ISO VG 46 (ESSO UNIVIS N 46)
- Brake fluid DOT3
- Brake fluid DOT4
- Brake fluid DOT5
- Water

See the block reference page for more information. The Examples section shows how you can get information on the fluids and their properties.

R2007b

Version: 1.2.1

New Features

Bug Fixes

Code Generation Now Available for SimHydraulics Models

Code generation has been implemented for models that include Simscape and SimHydraulics blocks. For more information, see Code Generation in the Simscape documentation.

R2007a

Version: 1.2

New Features

Bug Fixes

Compatibility Considerations

SimHydraulics Now Requires Simscape

SimHydraulics now depends on and requires Simscape, the platform for all Physical Modeling products, which includes common Physical Modeling utilities and block libraries.

Block Libraries Moved from SimHydraulics to Simscape

The Foundation and Utilities block libraries that used to be included in SimHydraulics (V1.0 and V1.1) are now part of Simscape product.

Sharing Models Using the Simscape Editing Modes

When working with SimHydraulics models, you now have a selection of two Simscape editing modes that allow full or restricted editing of models.

- The Restricted mode requires SimHydraulics software to be installed, but does not require a license. It allows you change a limited set of model parameters, but not the blocks or connections, in a SimHydraulics model.
- The Full mode requires SimHydraulics software to be installed with a license. It allows you to change anything in a SimHydraulics model.

New SimHydraulics Blocks

The new blocks introduced in Version 1.2 are listed below:

- Centrifugal Pump
- Single-Acting Rotary Actuator
- Double-Acting Rotary Actuator
- Hydraulic Single-Acting Valve Actuator
- Hydraulic Double-Acting Valve Actuator
- Valve Hydraulic Force
- Spool Orifice Hydraulic Force

Initial Conditions Added for Certain Blocks

Several blocks now have a parameter that specifies the initial condition for use in computing the block's initial state at the beginning of a simulation run. Note that some of

these blocks, which used to be included in SimHydraulics (V1.0 and V1.1), are now part of Simscape product. The following is a complete list of blocks where you can specify an initial condition through the block dialog box:

- Gas-Charged Accumulator
- Spring-Loaded Accumulator
- Constant Volume Chamber
- Variable Volume Chamber
- Fluid Inertia
- Inertia
- Mass
- PS Integrator
- Rotational Spring
- Translational Spring

For details, see the block reference pages.

Compatibility Considerations

In this version, there is a difference in the way the initial conditions are computed, and as a result, the blocks that have an initial condition parameter work differently than they used to in the previous version.

Block Library Links Must Be Resolved

All SimHydraulics blocks in your models must now have resolved block library links. You can neither disable nor break these library links. This is a global requirement of Simscape modeling environment. Consult the Simscape documentation for further details.

Compatibility Considerations

If you have an existing SimHydraulics model with disabled or broken links from SimHydraulics blocks to the SimHydraulics block library, you must restore all the broken block library links for your model to be valid.

If you have disabled or broken the SimHydraulics library link for blocks that you have customized and want to keep these modified blocks in your model, you must move these modified blocks to your own custom library or libraries, then copy the block instances that you need to your model.

You must still restore the block link to its parent library, whether that parent library is SimHydraulics or your own.

Changes to SimHydraulics Demos

The following demos have been added in Version 1.2:

| Demo Name | Description |
|--|---|
| Hydraulic Actuator with Two-Chamber Snubbers (sh_actuator_with_2_chamber_snubbers) | The reciprocal actuator demonstrated in this model is equipped with snubbers (cushions) on both sides of the cylinder. |
| Digital Hydraulic Actuator (sh_digital_hydraulic_actuator) | The digital hydraulic actuator consists of three double-acting cylinders mounted in the same shell and interconnected through the hard stops. |
| Hydraulic Actuator with Load-Sensing Variable-Displacement Pump (sh_hydraulic_actuator_load_sensing_pump) | The circuit demonstrates usage of a load-sensing and pressure-limiting unit in a conventional reciprocal system with variable load on the forward stroke. |
| Hydraulic Actuator with Telescopic Cylinder (sh_hydraulic_actuator_telescopic_cylinder) | The actuator is built around a telescopic hydraulic cylinder, which is equipped with three rods interacting with each other through hard stops. |
| Closed-Circuit Reciprocal Actuator (sh_hydraulic_closed_circuit_reciprocal_actuator) | The demo illustrates a closed-circuit electrohydraulic actuator driven by a variable-velocity electrical motor. |
| Power-Assisted Steering Mechanism (sh_hydraulic_power_assisted_steering) | The model represents a simplified version of a power-assisted steering mechanism showing all its major parts. |
| Hydraulic System with Servo-Valve (sh_hydraulic_system_with_servo_valve) | The demo represents the model of a two-stage servo-valve with a 4-way, 3-position spool valve in the power stage and a flapper-nozzle amplifier in the pilot stage. |

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| Hydraulic Transmission with Secondary Control (sh_hydraulic_transmission_secondary_control) | The system demonstrates usage of the so-called secondary control in hydrostatic transmissions with a variable-displacement motor. |
| Hydrostatic Transmission with Shuttle Valve (sh_hydrostatic_transmission_shuttle_valve) | The circuit demonstrates a hydrostatic transmission with a shuttle valve in the control unit. |
| Hydraulic Circuit with Load-Sensing Velocity Control (sh_load_sensing_velocity_control) | The circuit is equipped with the load-sensing velocity regulator installed between the pump and directional valve. |
| Oscillating Hydraulic Mechanism (sh_oscillating_hydraulic_mechanism) | The oscillating hydraulic mechanism consists of a single-acting hydraulic rotary actuator, winch, flow control valve, two-position electrohydraulic valve, and power and control units. |
| Reciprocal Actuator with Counterbalance Valves (sh_reciprocal_actuator_ctrb_valves) | The actuator is built of a double-acting cylinder, directional valve, flow control, block of counterbalance valves, power unit, replenishment arrangement, and a control unit. |
| Sequencing Circuit with Rotary Actuators (sh_sequencing_circuit_rotary_actuators) | The sequence circuit is based on four check valves installed in both pressure and return lines of the second rotary actuator. |

The following demos that used to be in SimHydraulics 1.1 are now part of Simscape product:

| Demo Name | Description |
|--|---|
| Simple Mechanical System (ssc_simple_mechanical_system) | This model is built of both rotational and translational mechanical blocks to illustrate their use in a system. |
| Mechanical System with Translational Friction (ssc_mechanical_system_translational_friction) | The demo illustrates a mass loaded with a spring and viscous damper. |
| Mechanical System with Translational Hard Stop (ssc_mechanical_system_translational_hardstop) | The demo illustrates two masses interacting through a hard stop. |

| | |
|---|---|
| Mechanical Rotational System with Stick-Slip Motion (ssc_rot_system_stick_slip) | This model demonstrates a mechanical rotational system, where a load is driven by a velocity source with a friction element between them, and stick-slip motion is developed in the regions of constant velocities. |
| Linkage Mechanism (ssc_linkage_mechanism) | The model demonstrates the use of the Lever block in a linkage mechanism. |

R2006b

Version: 1.1

New Features

Bug Fixes

Linearization Support

The Simulink `linmod` and `dlinmod` commands create continuous- or discrete-time linear time-invariant (LTI) state-space models from Simulink models. You can now use these commands to generate an LTI state-space model from a model containing SimHydraulics components.

There are two basic ways `linmod` and `dlinmod` can be used, and the behavior of linearization differs depending on which method is chosen. If `linmod mdl` is called (that is, the arguments for time, state, and input are not provided), then consistent initial conditions are solved for in the same way as on the first step of a simulation. If you call `linmod mdl, t, x, u`, it is particularly important to provide it with a consistent state to linearize about. For more information, see *Linearizing at an Operating Point* in the Simscape User's Guide.

New Solver Option Allows Starting Transient Analysis from a Steady State

A new solver option allows you to specify that simulation starts from a steady state. Steady state means that the system variables are no longer changing with time.

If you select the **Start simulation from steady state** check box in the Solver block dialog, the solver attempts to find the steady state that would result if the inputs to the system were held constant for a sufficiently large time, starting from the initial state obtained from the initial conditions computation. Although the solver tries to find the particular steady state resulting from the given initial conditions, it is not guaranteed to do so. All that is guaranteed is that if the steady-state solve succeeds, the state found is a steady state (within tolerance). Simulation then starts from this steady state.

Note If the simulation fails at or near the start time when you use the **Start simulation from steady state** option, consider clearing the check box and simulating with the plain initial conditions computation only.

Extended Functionality for Working with Physical Units

Version 1.1 provides the following commands that help you specify the physical units for your system:

-
- `pm_adddimension`
 - `pm_addunit`
 - `pm_getunits`

Unit names are defined in the `pm_units.m` file, which is shipped with the product. You can open this file to see how the physical units are defined, and also as an example when adding your own units. This file is located in the directory `matlabroot\toolbox\physmod\pm_util\pm_util`.

Use the `pm_getunits` command to get an up-to-date list of units currently defined in your unit registry. Use the `pm_adddimension` and `pm_addunit` commands to define additional units.

New SimHydraulics Blocks

The new blocks introduced in Version 1.1 are listed below:

- Annular Orifice
- Cylinder Friction
- Reservoir
- Elbow
- Pipe Bend
- T-junction
- Gradual Area Change
- Sudden Area Change
- Variable-Displacement Motor
- Variable-Displacement Pump
- Shuttle Valve
- PS Product
- PS Divide

R2006a+

Version: 1.0

New Features

Product Introduction

SimHydraulics software is a modeling environment for the engineering design and simulation of hydraulic power and control systems within Simulink and MATLAB. It is based on the Physical Network approach and contains a comprehensive library of hydraulic blocks, as well as one-dimensional translational and rotational mechanical elements and utility blocks.

SimHydraulics software key features are:

- Enables modeling and simulation of hydraulic power and control systems in Simulink
- Provides intuitive and convenient description of multidomain models based on physical networks
- Includes a library of hydraulic components, such as pumps, valves, accumulators, and pipelines, that account for effects such as fluid compressibility, turbulence transition, and fluid inertia
- Provides foundation library of hydraulic building blocks, as well as fundamental mechanical and mathematical elements, to enable efficient extension and customization of models
- Provides customizable library of hydraulic fluids

SimHydraulics software employs a network approach to model building. Components in the network correspond to physical elements, such as pumps, motors, valves, etc. The lines that join the components correspond to physical connections that transmit power between components. Unlike traditional Simulink block diagrams, these connections are non-directional and do not require the user to resolve the causality of the system while building the model. SimHydraulics libraries contain more than 75 models of hydraulic and mechanical components. All the models were developed to be easily characterized by data normally available in manufacturer's catalogs or data sheets. Building a model of a system is analogous to assembling the actual physical system with off-the-shelf components. The end result is a hydraulic circuit schematic in concurrence with ISO 1219 Fluid Power Standard.

SimHydraulics limitations are:

- Explicit solvers are not currently supported. Only the following solvers are supported: ode15s, ode23t, and ode14x.
- A SimHydraulics physical network should not exist within a Simulink algebraic loop. This means that you should not directly connect an output of a PS-Simulink

Converter block to an input of a Simulink-PS Converter block of the same physical network.

- Code generation is not currently supported.

